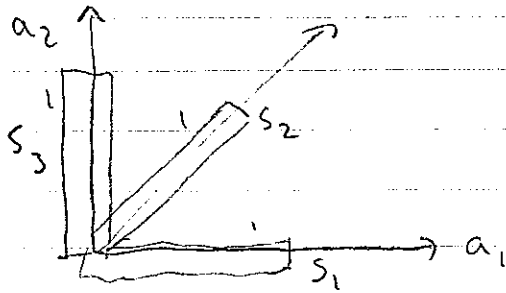


# Tutorial Four Notes - for Assignment 3

(1) 3 strain gauges measure the change in length of wires or rods, etc., deployed  $45^\circ$  apart in a plane as shown:

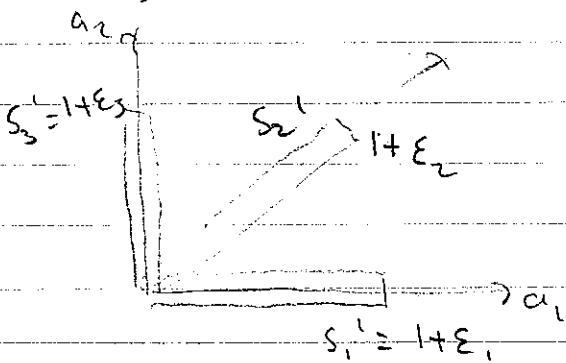


original: lengths are  $S_1 = S_2 = S_3 = 1$

Assume  $\hat{a}_3$  has no change (into + out of paper)

New lengths: have had changes

- $\epsilon_1$  per unit length in direction of  $S_1$ , which is  $a_1$
- $\epsilon_2$  " " " " " " " " " " " "  $S_2$ , which is  $45^\circ$  to  $a_1$
- $\epsilon_3$  " " " " " " " " " " " "  $S_3$ , which is  $a_2$



Calculate Strain Tensor  $E$  using the strain gauge measurements

Remember formula:

$$E_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial a_j} + \frac{\partial u_j}{\partial a_i} \right) \text{ in the } \hat{a}_1, \hat{a}_2, \hat{a}_3 \text{ system.}$$

$$S_1' = \hat{a}_1 (1 + \epsilon_1)$$

$$\Delta S_1 = S_1' - S_1 = \epsilon_1 \hat{a}_1$$

$$S_2' = (1 + \epsilon_2) \cos \theta \hat{a}_1 + (1 + \epsilon_3) \sin \theta \hat{a}_2$$

$$\Delta S_2 = \epsilon_2 \cos \theta \hat{a}_1 + \epsilon_3 \sin \theta \hat{a}_2$$

$$S_3' = \hat{a}_2 (1 + \epsilon_3)$$

$$\Delta S_3 = \epsilon_3 \hat{a}_3$$

$$E = \begin{pmatrix} E_{11} & E_{12} \\ E_{12} & E_{22} \end{pmatrix}$$

Consider the unit vector  $\hat{a}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$$\Delta S_1 = \Delta u_1 = E \hat{a}_1 = E \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} E_{11} \\ E_{12} \end{pmatrix}$$

The component of this in the direction of the strain gauge is dot product:

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} E_{11} \\ E_{12} \end{pmatrix} = E_{11} = \epsilon_1 \quad \text{as defined.}$$

Similarly the component in direction  $\hat{a}_2$  of the strain gauge is

$$\Delta S_2 = \Delta u_2 = E \hat{a}_2 = E \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} E_{12} \\ E_{22} \end{pmatrix}$$

Component of strain in direction  $\hat{a}_2$  is

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} E_{12} \\ E_{22} \end{pmatrix} = E_{22} = \epsilon_3 \quad \text{as defined}$$

Similarly for  $S^{21} \rightarrow$

$$\begin{pmatrix} E_{11} & E_{12} \\ E_{12} & E_{22} \end{pmatrix} = \begin{pmatrix} \epsilon_1 & E_{12} \\ E_{12} & \epsilon_3 \end{pmatrix}$$

using  $\theta = 45^\circ$

$$\begin{pmatrix} \epsilon_1 & E_{12} \\ E_{12} & \epsilon_3 \end{pmatrix} \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} = \begin{pmatrix} \epsilon_1 \cos \theta + E_{12} \sin \theta \\ E_{12} \sin \theta + \epsilon_3 \sin \theta \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} \epsilon_1 + E_{12} \\ E_{12} + \epsilon_3 \end{pmatrix}$$

$$\text{or } \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

Component of strain in this direction is

$$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} \epsilon_1 + E_{12} \\ E_{12} + \epsilon_3 \end{pmatrix} = \frac{1}{2} [\epsilon_1 + 2E_{12} + \epsilon_3] = \epsilon_2$$

$$S_0 \quad E_1 + 2E_{12} + E_3 = 2E_2$$

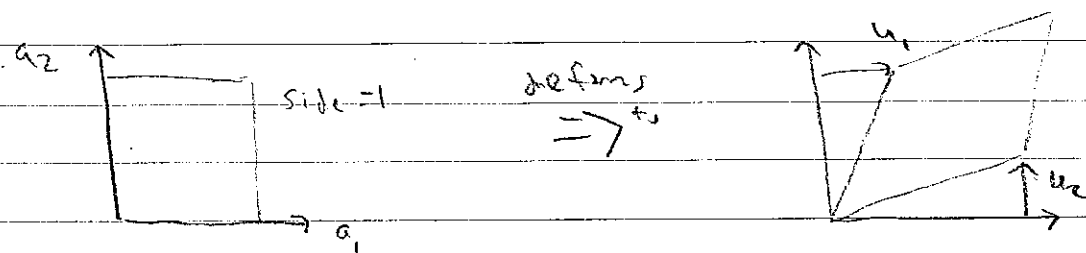
$$2E_{12} = 2E_2 - E_1 - E_3$$

$$E_{12} = E_2 - \frac{1}{2}(E_1 + E_3)$$

$$E = \begin{pmatrix} E_1 & E_2 - \frac{1}{2}(E_1 + E_3) \\ E_2 - \frac{1}{2}(E_1 + E_3) & E_3 \end{pmatrix}$$

4

Tutorial Problem 2.



No deformation or change in  $\hat{a}_3$  direction: plane strain  
 So if  $u_1$  and  $u_2$  are proportional with different proportionality constants  $k$

$$u_1 = k_1 a_2 \quad u_2 = k_2 a_1$$

Find Strain + Rotation tensors, the equivalent rotation vector, the principal strains, the principal axes + the dilatation

Example w/  $k_1 = k_2$  is in lectures

$$E_{3i} = W_{3i} = 0 \text{ for all } i$$

$$E = \frac{1}{2} \left( \frac{\partial u_i}{\partial a_j} + \frac{\partial u_j}{\partial a_i} \right)$$

$$E_{11} = \frac{1}{2} \left( \frac{\partial u_1}{\partial a_1} + \frac{\partial u_1}{\partial a_1} \right) = k_1 \cdot 0$$

$$E_{12} = \frac{1}{2} \left( \frac{\partial u_1}{\partial a_2} + \frac{\partial u_2}{\partial a_1} \right) = \frac{k_1 + k_2}{2}$$

$$E_{22} = \frac{1}{2} \left( \frac{\partial u_2}{\partial a_2} + \frac{\partial u_2}{\partial a_2} \right) = 0$$

$$E_{21} = \frac{1}{2} \left( \frac{\partial u_2}{\partial a_1} + \frac{\partial u_1}{\partial a_2} \right) = E_{12}$$

$$E = \begin{pmatrix} 0 & \frac{k_1 + k_2}{2} \\ \frac{k_1 + k_2}{2} & 0 \end{pmatrix}$$

$$W_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right)$$

$$W = \begin{pmatrix} 0 & \frac{k_1 - k_2}{2} \\ \frac{k_2 - k_1}{2} & 0 \end{pmatrix}$$

rotation vector  $W = -(W_{23}, W_{31}, W_{12})^T = - \begin{pmatrix} 0 \\ 0 \\ \frac{k_1 - k_2}{2} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \frac{k_2 - k_1}{2} \end{pmatrix}$

To get the principal strains + principal axes, need to diagonalize the strain tensor:

To diagonalize the tensor, find its eigenvalues + eigenvectors  
 $Eg = \lambda g$

$$\begin{pmatrix} 0 - \lambda & \frac{k_1 + k_2}{2} \\ \frac{k_1 + k_2}{2} & 0 - \lambda \end{pmatrix} = 0$$

$$\det \begin{pmatrix} \dots \end{pmatrix} = \lambda^2 - \left(\frac{k_1 + k_2}{2}\right)^2 = 0$$

$$\left[ \lambda - \left(\frac{k_1 + k_2}{2}\right) \right] \left[ \lambda + \left(\frac{k_1 + k_2}{2}\right) \right] = 0$$

$$\lambda = \pm \frac{k_1 + k_2}{2}$$

If  $\lambda_1 = \frac{k_1 + k_2}{2}$  then  $\begin{pmatrix} -\frac{k_1 + k_2}{2} & \frac{k_1 + k_2}{2} \\ \frac{k_1 + k_2}{2} & -\frac{k_1 + k_2}{2} \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \end{pmatrix} = 0$

$$-e_1 \left(\frac{k_1 + k_2}{2}\right) + e_2 \left(\frac{k_1 + k_2}{2}\right) = 0$$

$e_1 = e_2 \rightarrow$  same e.g. twice

For  $\lambda_2 = -\frac{k_1 + k_2}{2}$   $\begin{pmatrix} \frac{k_1 + k_2}{2} & \frac{k_1 + k_2}{2} \\ \frac{k_1 + k_2}{2} & \frac{k_1 + k_2}{2} \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \end{pmatrix} = 0$

$$\begin{aligned} \lambda_1 &= \frac{k_1 + k_2}{2} \quad \hat{e}_1 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \\ \lambda_2 &= -\frac{k_1 + k_2}{2} \quad \hat{e}_2 = \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \end{aligned}$$

$$e_1 = -e_2$$

$A = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$  = matrix of eigen vectors as columns  
 $A E A^T$  should =  $E$   
 check:

where we have normalized the eigen vectors

$$A E A^T = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & \frac{k_1 + k_2}{2} \\ \frac{k_1 + k_2}{2} & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} \left(\frac{k_1 + k_2}{2}\right) & \frac{1}{\sqrt{2}} \left(\frac{k_1 + k_2}{2}\right) \\ \frac{1}{\sqrt{2}} \left(\frac{k_1 + k_2}{2}\right) & \frac{1}{\sqrt{2}} \left(\frac{k_1 + k_2}{2}\right) \end{pmatrix}$$

eigenvectors = principal axes

$$\begin{pmatrix} -\frac{k_1 + k_2}{2} & 0 \\ 0 & \frac{k_1 + k_2}{2} \end{pmatrix} \quad Q = D \quad \text{Principal strain} = \pm \frac{k_1 + k_2}{2}$$

Dilatation = trace of strain = 0